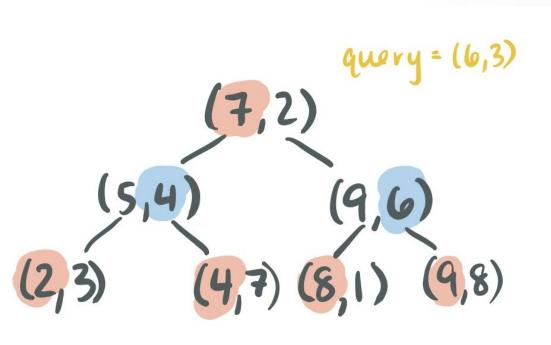
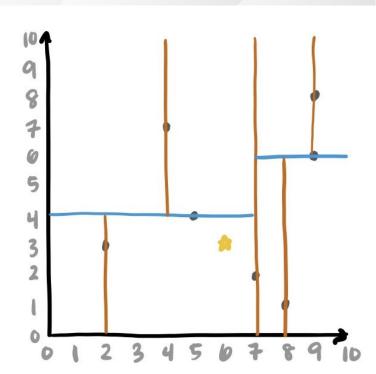


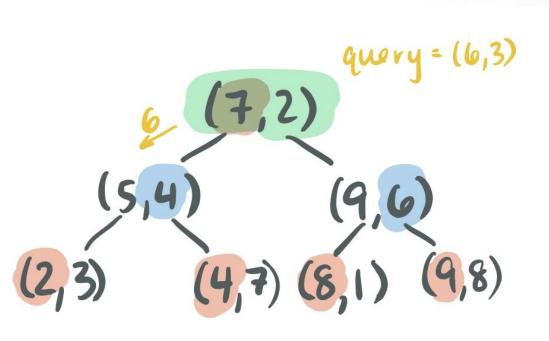
#### **KD Trees**

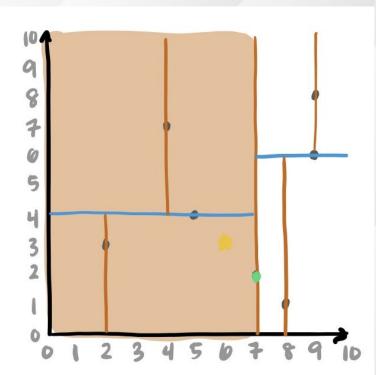
# **Learning Objectives**

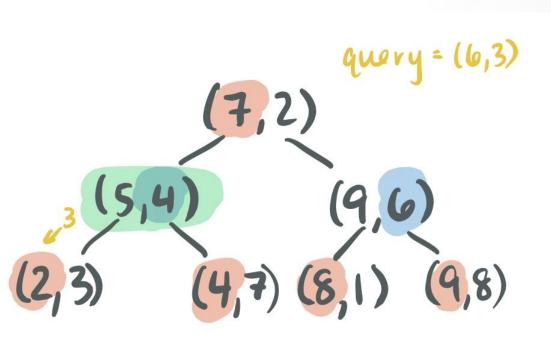
1. Use a KD Tree to find the nearest point in 2D

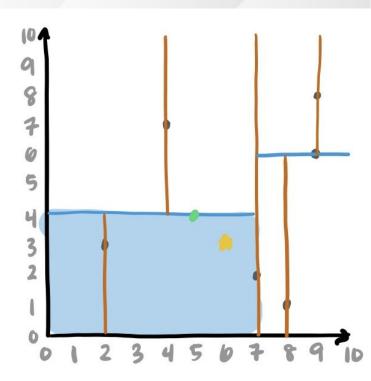


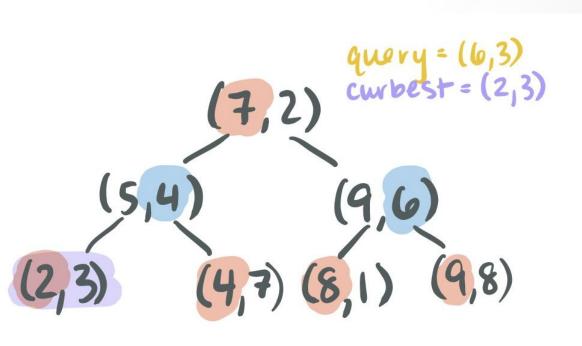


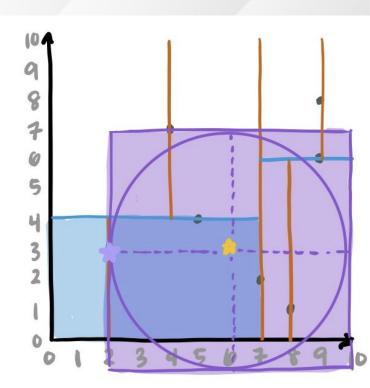






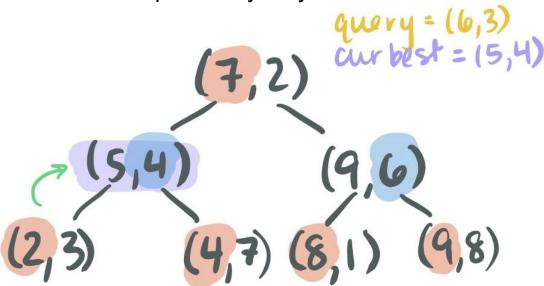


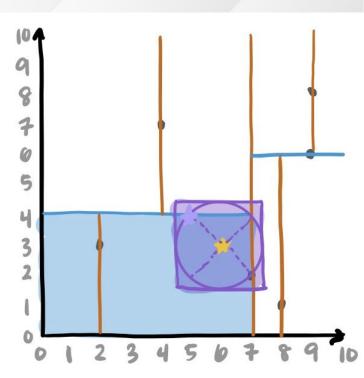


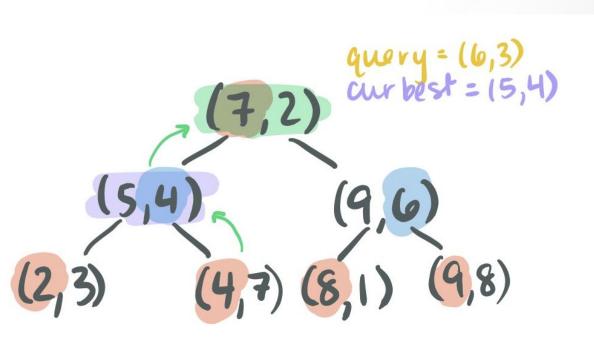


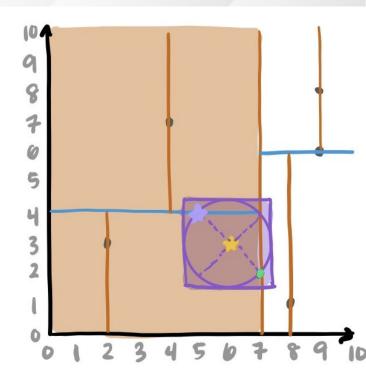
Backtracking: start recursing backwards

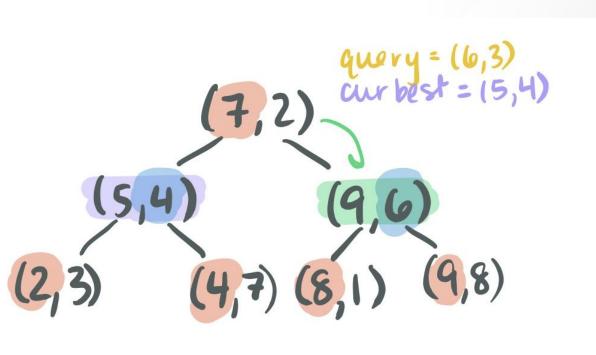
-- store "best" possibility as you trace back

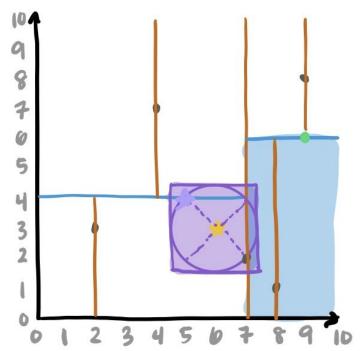


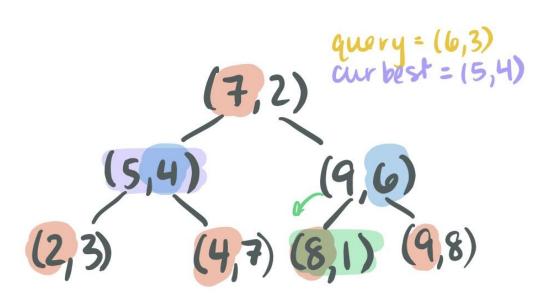


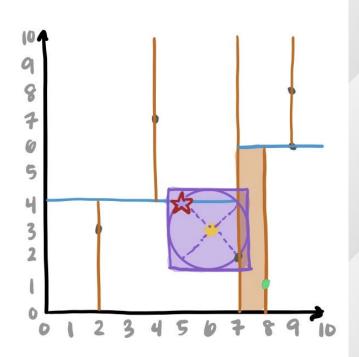












BEST: (5,4)